

Statecharts for the many: Algebraic State Transition Diagrams

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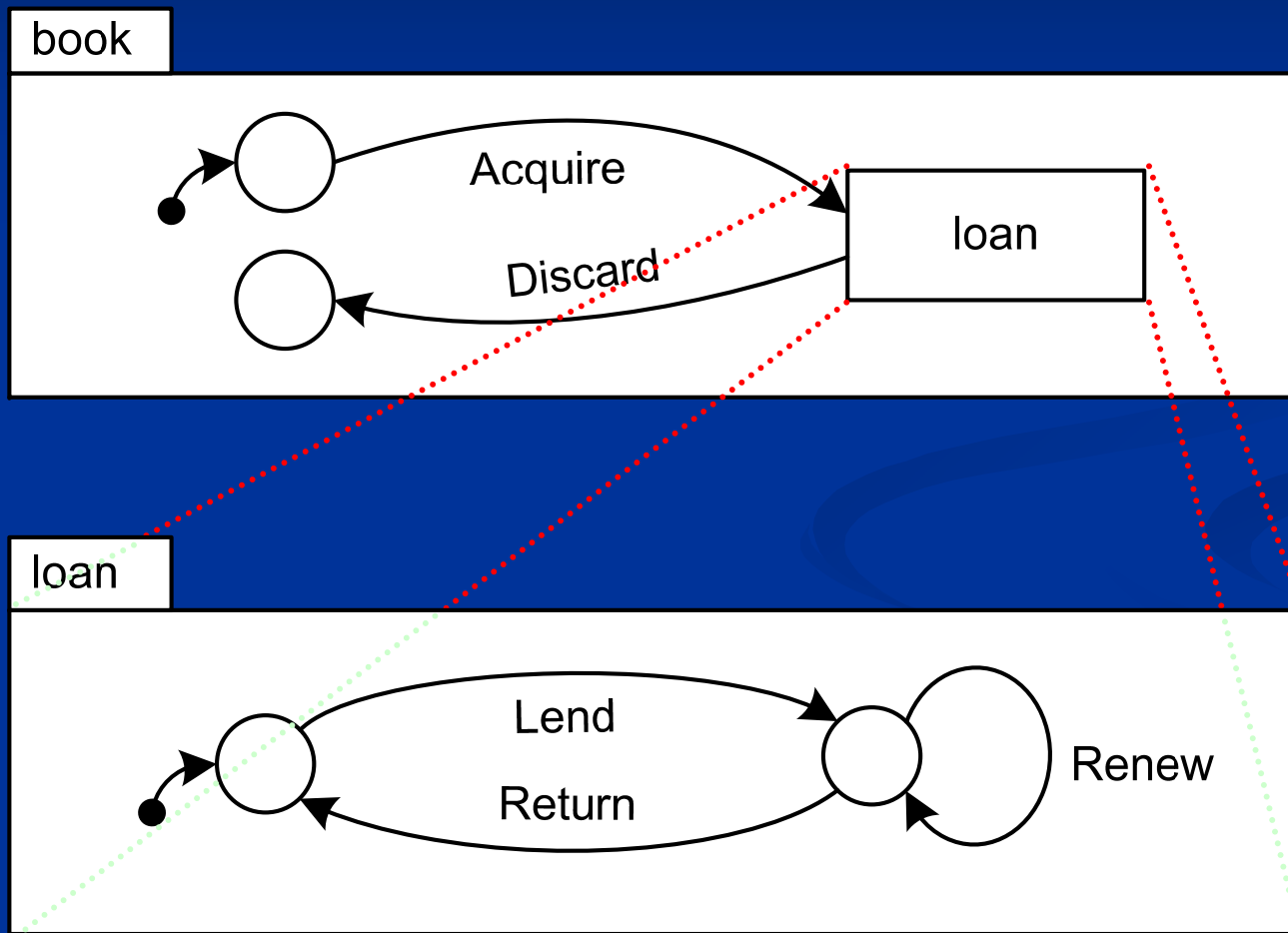
Plan

- Statecharts and information system specifications
- ASTD : Algebraic State Transition Diagrams
- Semantics of ASTD
- Conclusion

Statecharts

- graphical notation
- hierarchy + orthogonality
 - hierarchical states
 - AND states (parallel)
 - OR states (choice)
- nice for single instance behaviour
- parameterized states in Harel's seminal paper (SCP 87)
 - “*never*” implemented or formalised

A library in statecharts

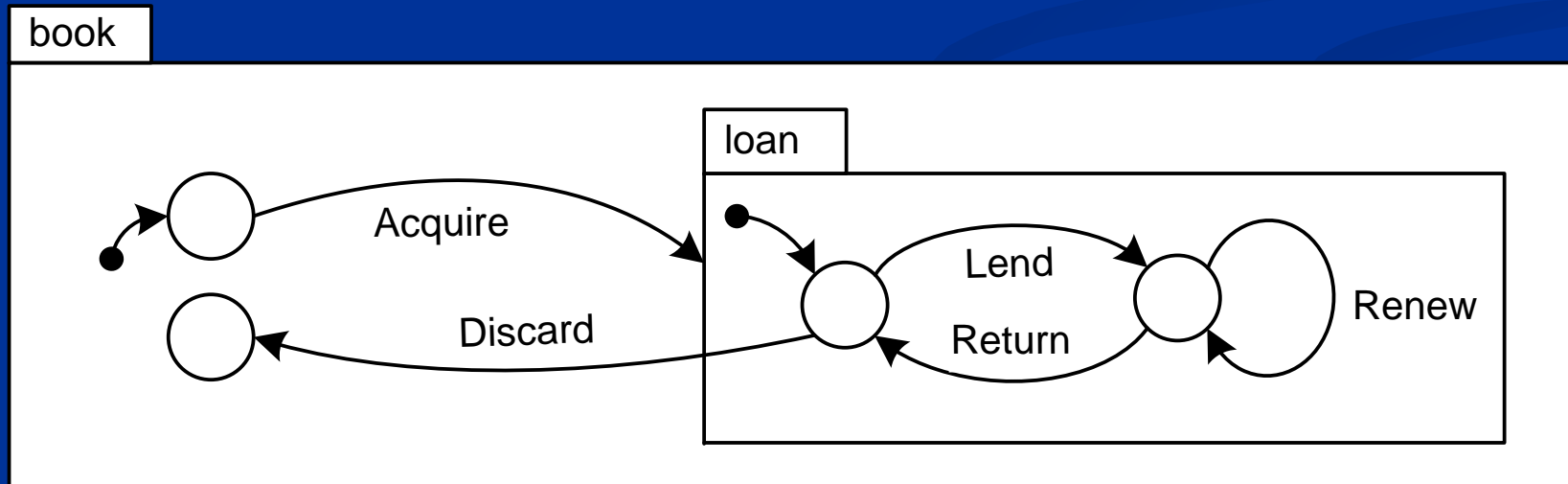


Problems

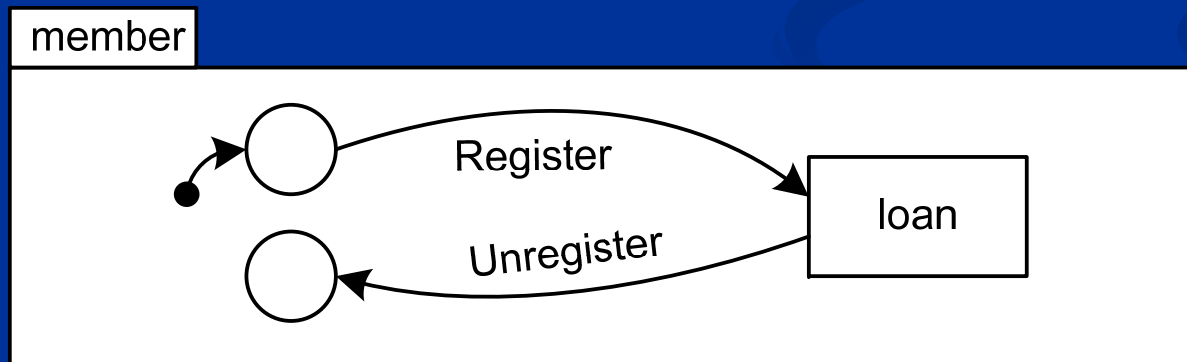
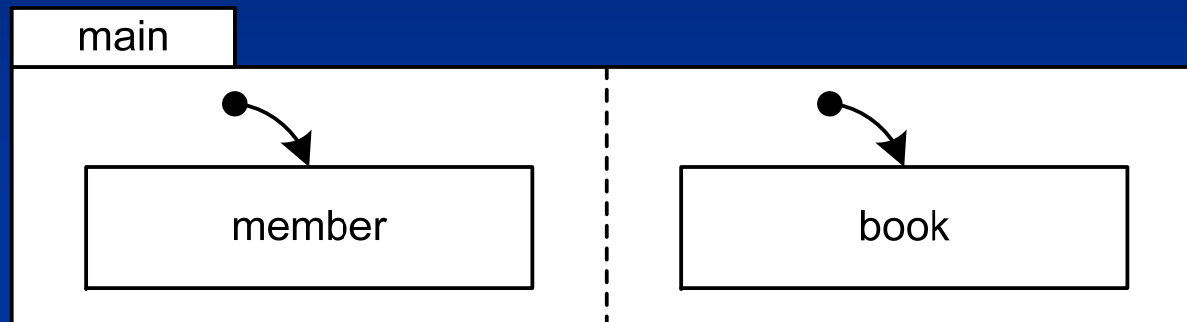
- only describes behaviour of a single book
 - how to deal with several books?
 - put n copies of book in parallel
 - not defined in statecharts or UML
 - available in ROSE RT, but it is not quite what we want here
- can discard an unreturned book
 - could add a guard to discard
 - unnecessary complexity
 - could make discard a transition from an inner state of loan
 - introduce coupling between book and loan

Potential solutions

- book knows about the structure of loan
 - makes loan less reusable
 - makes maintenance more difficult



Adding members



Problems

- a member can borrow several books in parallel
 - can't "easily" express that in statecharts or UML
 - State explosion
- two calls to loan
 - one in member, one in book
 - they both get the lend event
 - OK if only one member
 - KO if we have several members trying to borrow the same book
 - could remove loan from member
 - must add guard to Unregister to check for completed loan
 - loose visual ordering constraint

Potential solutions

- remove loan from member
 - loose visual ordering constraint between member and loan
 - replaced by a guard
 - need state variable



The single instance view: A weakness of statecharts

- both statecharts and UML state machines are designed to represent a single instance
 - eg, controller, object of a class, etc
- they offer no convenient means to express relationships between multiple instances
- in practice, designers only describe the single instance behaviour
 - leave it to the implementer to figure out the multiple instance case

A solution: Process algebra

- CCS, CSP, ACP, LOTOS, EB³, ...
- algebra
 - operators to combine process expressions
 - sequence, choice, interleave, synchronisation, guard, ...
 - quantification
 - operators are the essence of abstraction
 - combine small units to build large units
 - operators foster abstraction by masking internal details

A Process expression for books

`book(b : BookId) =`

Sequential
composition

`Acquire(b, _)`

matches any
value

`loan(_, b)`

Kleene
closure

`Discard(b)`

A process expression for loans

loan(mId:Member, IDbId:BookID) =

$\text{nbLoans}(mId) < \text{maxNbLoans}(mId)$

$\Rightarrow \text{Lend}(mId, bId)$

•

$\text{Renew}(bId)^*$

•

$\text{Return}(bId)$

guard

A process expression for members

$\text{member}(m : \text{MemberId}) =$

$\text{Register}(m, _, _)$

•

$(\exists b : \text{BookId} : \text{loan}(m, b)^*)$

•

$\text{Unregister}(m)$

interleave
quantification
over all books

Interleave quantification

$$\begin{aligned} & \exists x : \{1,2,3\} : P(x) \\ = & \\ & P(1) \exists P(2) \exists P(3) \end{aligned}$$

Main process expression

main =

(|| b : BookId : **book**(b)^{*})

||

(|| m : MemberId : **member**(m)^{*})



Synchronisation over
common actions

Synchronisation over common actions

$a(1) \cdot b(1) \cdot c(1)$

\parallel

quantified
choice

$|x : T : a(x) \cdot b(x) \cdot c(2)$

$=$

$a(1) \cdot b(1) \cdot \text{STOP}$

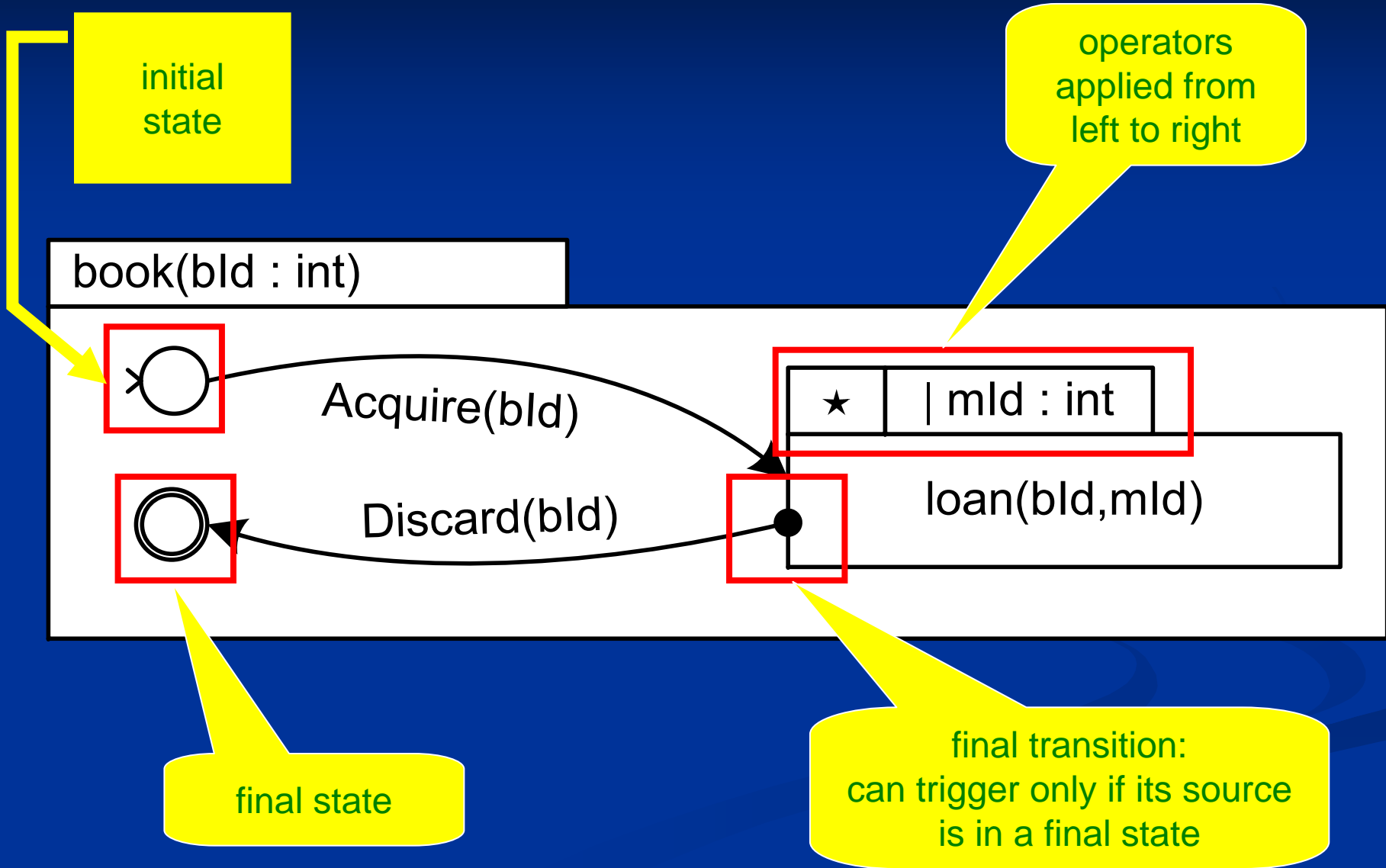
ASTD

- Algebraic State Transition Diagrams
- $ASTD = \text{statecharts} + \text{process algebra}$
 - graphical notation
 - power of abstraction
- statecharts become elementary process expressions
 - combine them using operators
- formal semantics
 - operational semantics

ASTD Operators

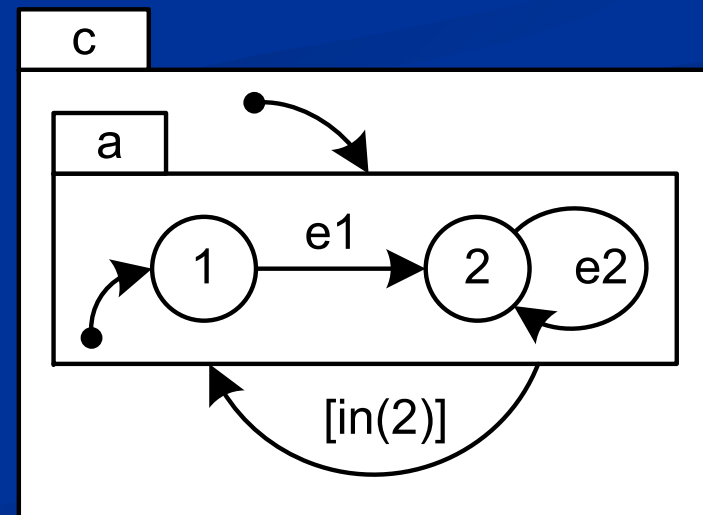
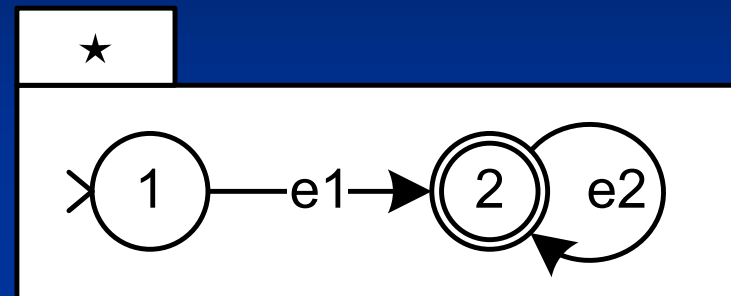
- \Rightarrow : sequence
- $|$: choice
 - $|_x$: quantified choice
- \star : Kleene closure
- \Rightarrow : guard
- $[[A]]$: parallel composition with synchronisation on A
 - $|||$ interleave, $||$ parallel composition
 - $|||_x$, $[[]_x$: quantified version
- **ASTD call** : allows recursive calls

A book ASTD



Closure applied to an ASTD

- ★ means execute the ASTD an arbitrary number of times, including 0
 - when the ASTD is in a final state, it can start again from its initial state
- example traces are
 - empty trace
 - $e1, e2, e2, \dots, e1, e1, e2, \dots$



The closure ASTD type

(\star, body)

- \star denotes the type constructor for a closure
- body is an ASTD (of any type)

The closure state type

- $\star\circ$ is the closure state type constructor
- $started?$ is a boolean value that indicates if its component has started its first iteration
- s is the state of its component

($\star\circ$, $started?$, s)

States of a closure

function that defines the initial state of an ASTD

closure ASTD

closure initial state

- is the initial state of its component

$$\mathit{init}((\star, b)) \triangleq (\star_{\circ}, \text{false}, \mathit{init}(b))$$

■ final states

- its initial state
- final states of its component

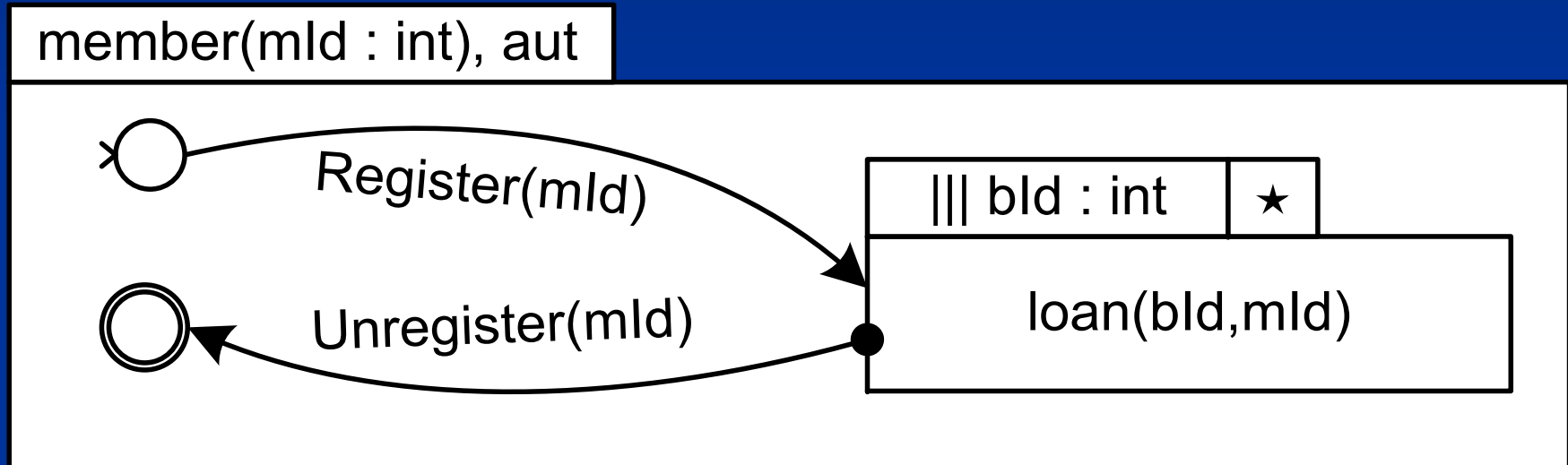
$$\mathit{final}((\star_{\circ}, \text{started?}, s)) \triangleq \mathit{final}_b(s) \vee \neg \text{started?}$$

function that determines if a state is final

Final state

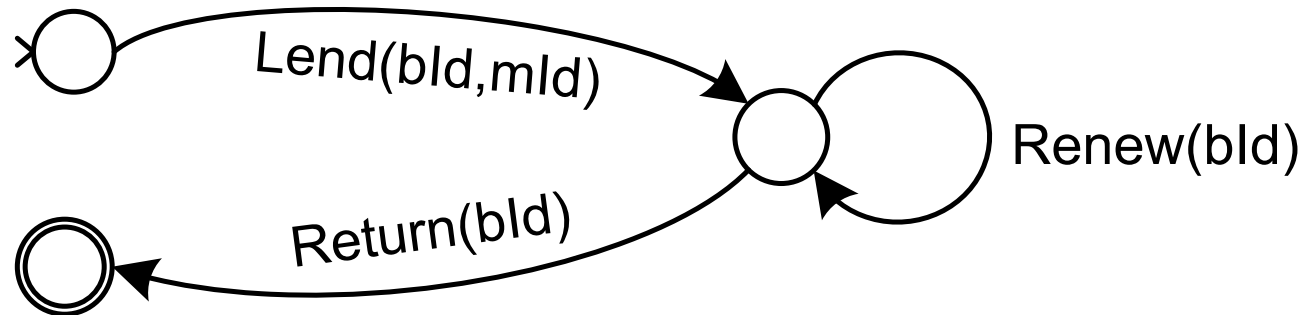
- an ASTD does not terminate when its current state is final
- a final state simply *enables* transitions of another ASTD within a
 - closure
 - sequence

A member ASTD

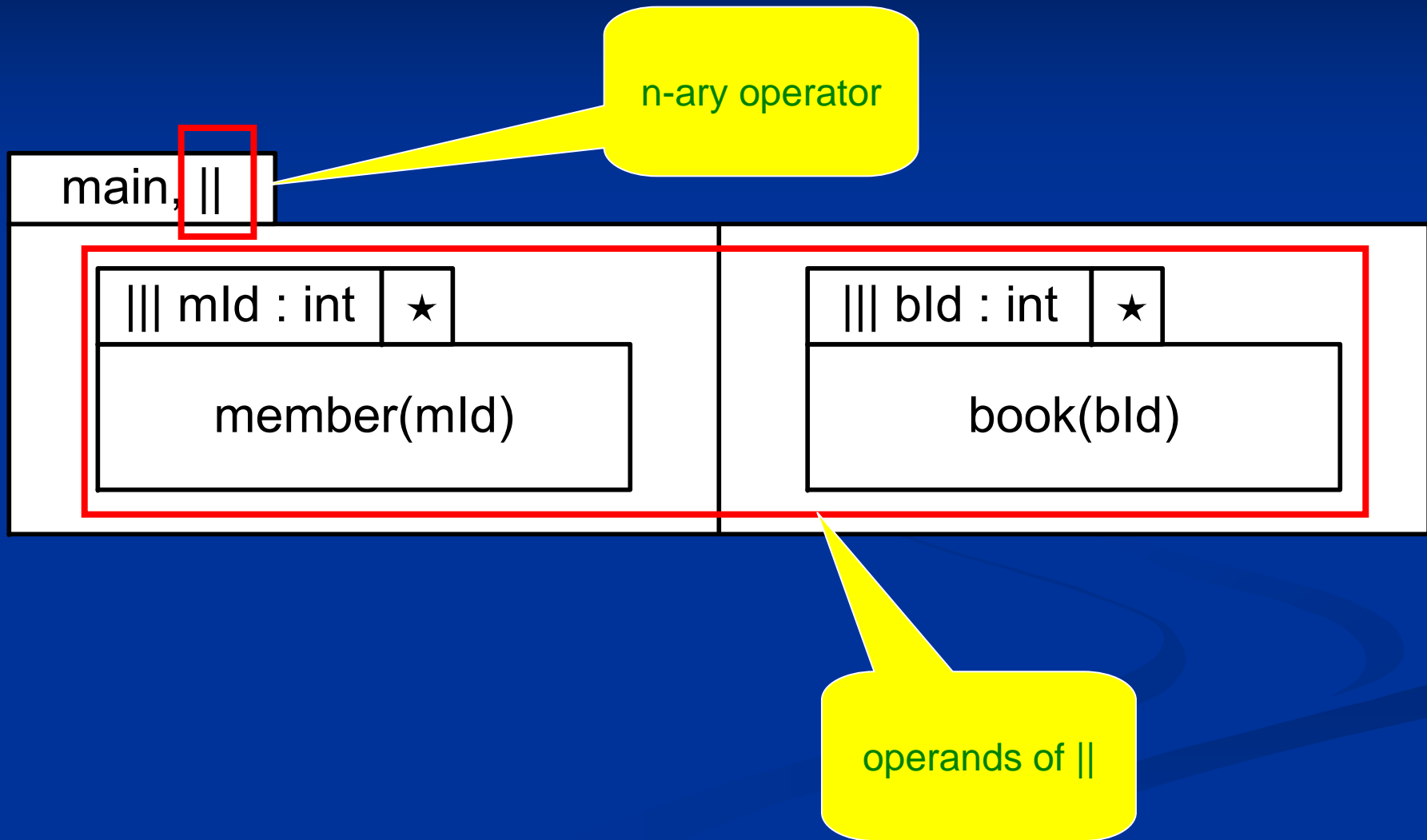


A loan ASTD

loan(bld : int, mld : int)



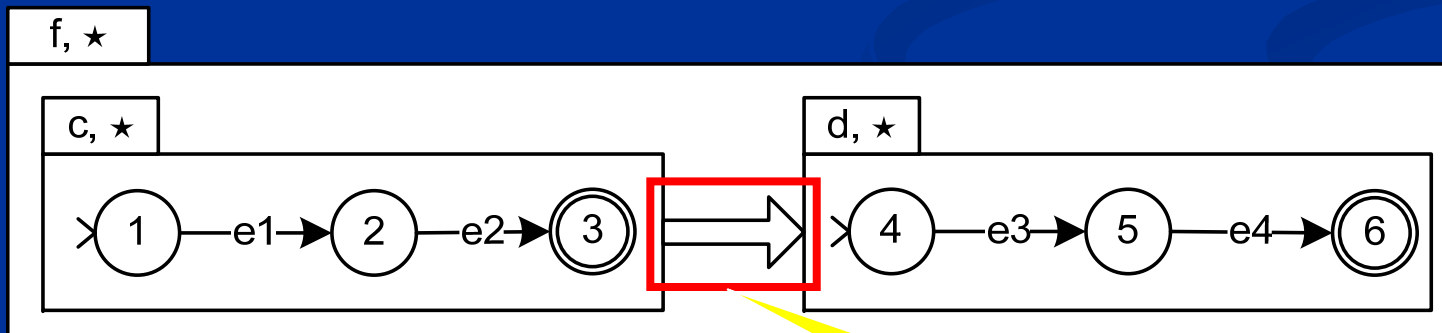
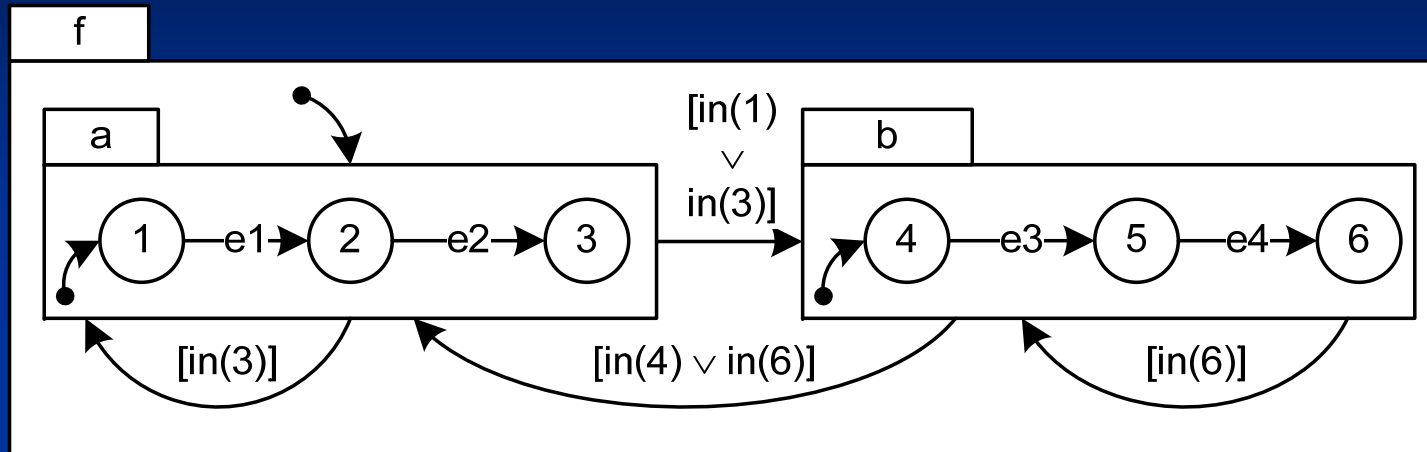
The main ASTD



Power of abstraction

- suppose you have two statecharts, **a** and **b**
- you want to compose them as follows
 - execute **a** an arbitrary number of times
 - then execute **b** an arbitrary number of times
 - then start over again, an arbitrary number of times
- can't do it in statecharts without peeking into **a** and **b**'s structure with guards
 - introduce a dependency between the compound and the components

Power of abstraction



sequential
composition

The sequence ASTD type

(\Rightarrow , left, right)

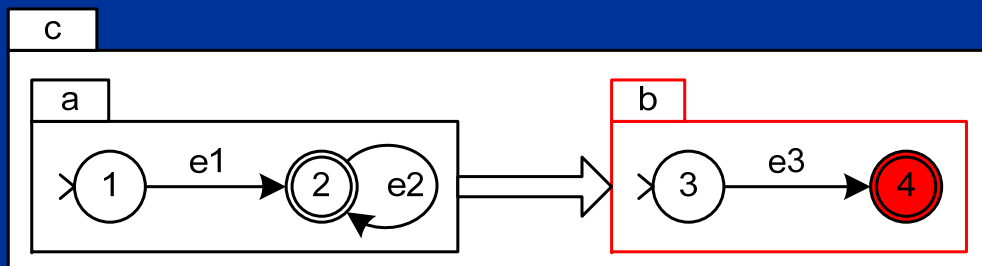
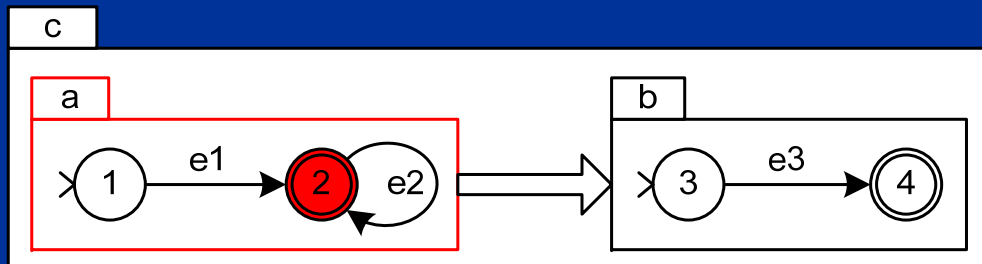
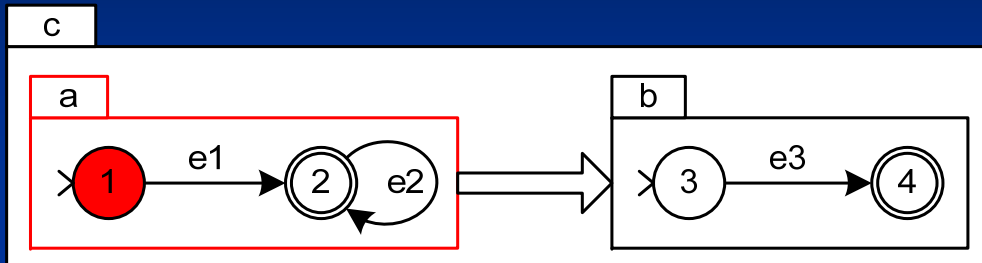
- \Rightarrow denotes the sequence ASTD type constructor
- **left** and **right** are ASTDs

The sequence state type

- $\Rightarrow \circ$ denotes the sequence state type constructor
- **side** denotes the current side of the sequence
 - left
 - right
- **s** denotes the state of the side component

$(\Rightarrow \circ, \text{side}, s)$

State transitions



$(\Rightarrow \circ, \text{left}, 1)$

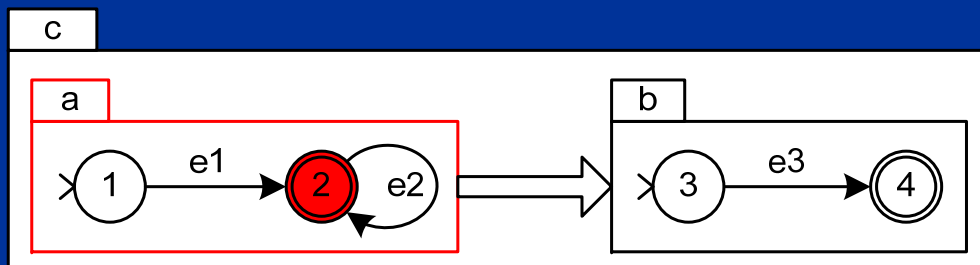
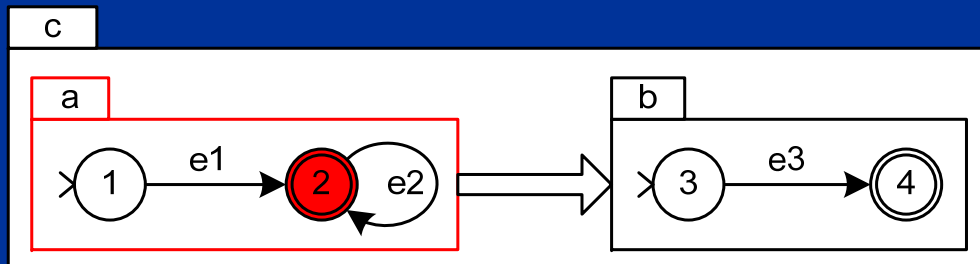
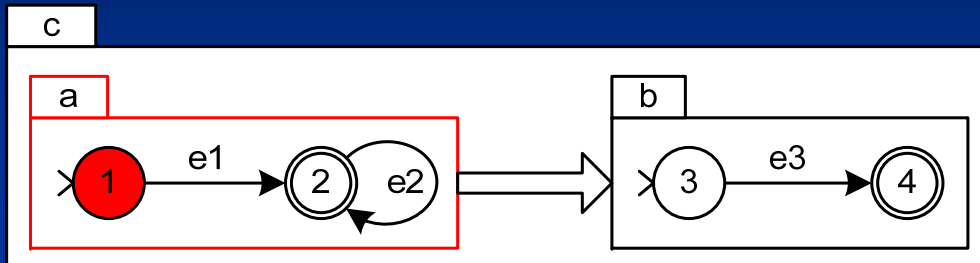
e1

$(\Rightarrow \circ, \text{left}, 2)$

e3

$(\Rightarrow \circ, \text{right}, 4)$

State transitions



$(\Rightarrow \circ, \text{left}, 1)$



e1

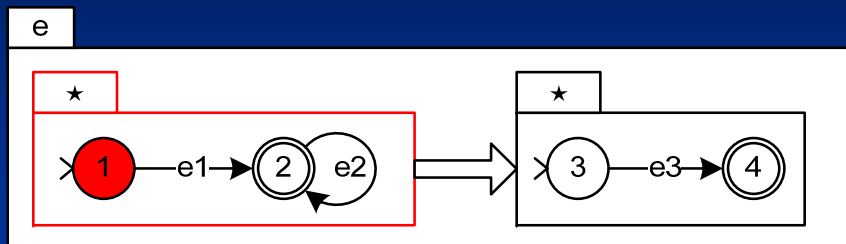
$(\Rightarrow \circ, \text{left}, 2)$



e2

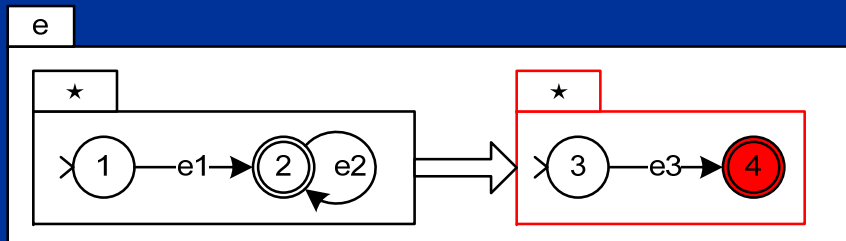
$(\Rightarrow \circ, \text{left}, 2)$

State transitions



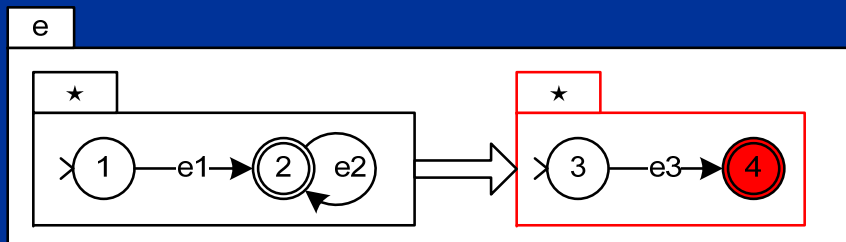
$(\Rightarrow \circ, \text{left}, (\star \circ, \neg \text{started}, 1))$

e3



$(\Rightarrow \circ, \text{right}, (\star \circ, \text{started}, 4))$

e3



$(\Rightarrow \circ, \text{right}, (\star, \text{started}, 4))$

Initial and final states of a sequence ASTD

$$\begin{aligned} \mathit{init}((\Rightarrow, l, r)) &\triangleq (\Rightarrow_{\circ}, \mathbf{left}, \mathit{init}(l)) \\ \mathit{final}((\Rightarrow_{\circ}, \mathbf{left}, s)) &\triangleq \mathit{final}_l(s) \wedge \mathit{final}_r(\mathit{init}(r)) \\ \mathit{final}((\Rightarrow_{\circ}, \mathbf{right}, s)) &\triangleq \mathit{final}_r(s) \end{aligned}$$

Operational semantics

- first used by Milner for CCS
- transitions

$$s \xrightarrow{\sigma} a \ s'$$

- ASTD a can execute σ from state s and move to state s'

Operational semantics

- transitions defined by a set of inference rules
- rules for each operator
- allows non-determinism
 - if several transitions can fire from s , then one is nondeterministically chosen
 - no priority

Inference rules

- first rules deals with environment, noted $(\llbracket \rrbracket)$, to manage variables introduced by
 - quantifications
 - process parameters

$$\text{env} \frac{s \xrightarrow{\sigma, (\llbracket \rrbracket)} s'}{s \xrightarrow{\sigma} s'}$$

Automaton reference rules

similar to traditional δ of an automaton

$$\text{aut}_1 \frac{\delta((\text{loc}, n_1, n_2), \sigma', g, \text{final?}) \quad \Psi}{(\text{aut}_o, n_1, h, s) \xrightarrow{\sigma, \Gamma} (\text{aut}_o, n_2, h', \text{init}(\nu(n_2)))}$$

execute an automaton transition

$$\Psi \triangleq ((\text{final?} \Rightarrow \text{final}_{\nu(n_1)}(s)) \wedge g \wedge \sigma' = \sigma \wedge h' = h \triangleleft \{n_1 \mapsto s\}) [\Gamma]$$

$$\text{aut}_6 \frac{s \xrightarrow{\sigma, \Gamma}_{\nu(n)} s'}{(\text{aut}_o, n, h, s) \xrightarrow{\sigma, \Gamma} (\text{aut}_o, n, h, s')}$$

execute a transition of the component

Closure inference rules

execute from the initial state of the component

$$\star_1 \frac{(final_b(s)[\Gamma] \vee \neg started?) \quad init(b) \xrightarrow{\sigma, \Gamma}_b s'}{(\star_o, started?, s) \xrightarrow{\sigma, \Gamma} (\star_o, \mathbf{true}, s')}$$

execute the component when started

$$\star_2 \frac{s \xrightarrow{\sigma, \Gamma}_b s'}{(\star_o, \mathbf{true}, s) \xrightarrow{\sigma, \Gamma} (\star_o, \mathbf{true}, s')}$$

Sequence inference rules

$$\Rightarrow_1 \frac{s \xrightarrow{\sigma, \Gamma}_l s'}{(\Rightarrow_{\circ}, \text{left}, s) \xrightarrow{\sigma, \Gamma} (\Rightarrow_{\circ}, \text{left}, s')}$$

execute on left

$$\Rightarrow_2 \frac{\text{final}_l(s)[\Gamma] \quad \text{init}(r) \xrightarrow{\sigma, \Gamma}_r s'}{(\Rightarrow_{\circ}, \text{left}, s) \xrightarrow{\sigma, \Gamma} (\Rightarrow_{\circ}, \text{right}, s')}$$

execute on right
when left is final

$$\Rightarrow_3 \frac{s \xrightarrow{\sigma, \Gamma}_r s'}{(\Rightarrow_{\circ}, \text{right}, s) \xrightarrow{\sigma, \Gamma} (\Rightarrow_{\circ}, \text{right}, s')}$$

execute the right
component

Choice: initial and final states

Choice state
($| \circ, \text{side}, s$)

$$\begin{aligned} \mathit{init}(|, l, r) &\triangleq (| \circ, \perp, \perp) \\ \mathit{final}(| \circ, \perp, \perp) &\triangleq \mathit{final}_l(\mathit{init}(l)) \vee \mathit{final}_r(\mathit{init}(r)) \\ \mathit{final}(| \circ, \mathbf{fst}, s) &\triangleq \mathit{final}_l(s) \\ \mathit{final}(| \circ, \mathbf{snd}, s) &\triangleq \mathit{final}_r(s) \end{aligned}$$

Choice inference rules

$$|_1 \frac{init(l) \xrightarrow{\sigma, \Gamma}_l s'}{(|_o, \perp, \perp) \xrightarrow{\sigma, \Gamma} (|_o, \mathbf{fst}, s')}$$

execute the first component
from its initial state

$$|_2 \frac{init(r) \xrightarrow{\sigma, \Gamma}_r s'}{(|_o, \perp, \perp) \xrightarrow{\sigma, \Gamma} (|_o, \mathbf{snd}, s')}$$

execute the second component
from its initial state

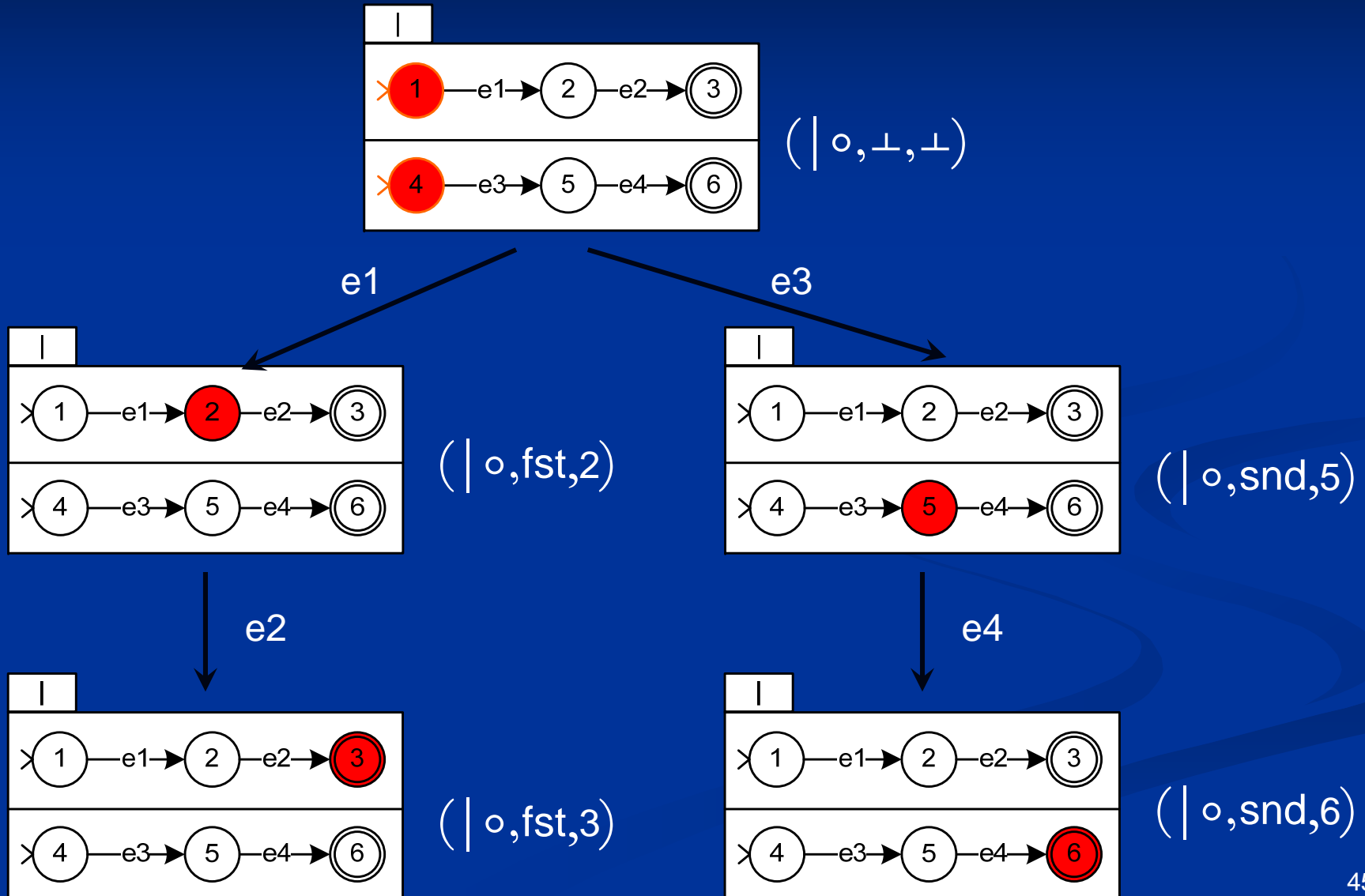
$$|_3 \frac{s \xrightarrow{\sigma, \Gamma}_l s'}{(|_o, \mathbf{fst}, s) \xrightarrow{\sigma, \Gamma} (|_o, \mathbf{fst}, s')}$$

execute the first component
when it has been selected

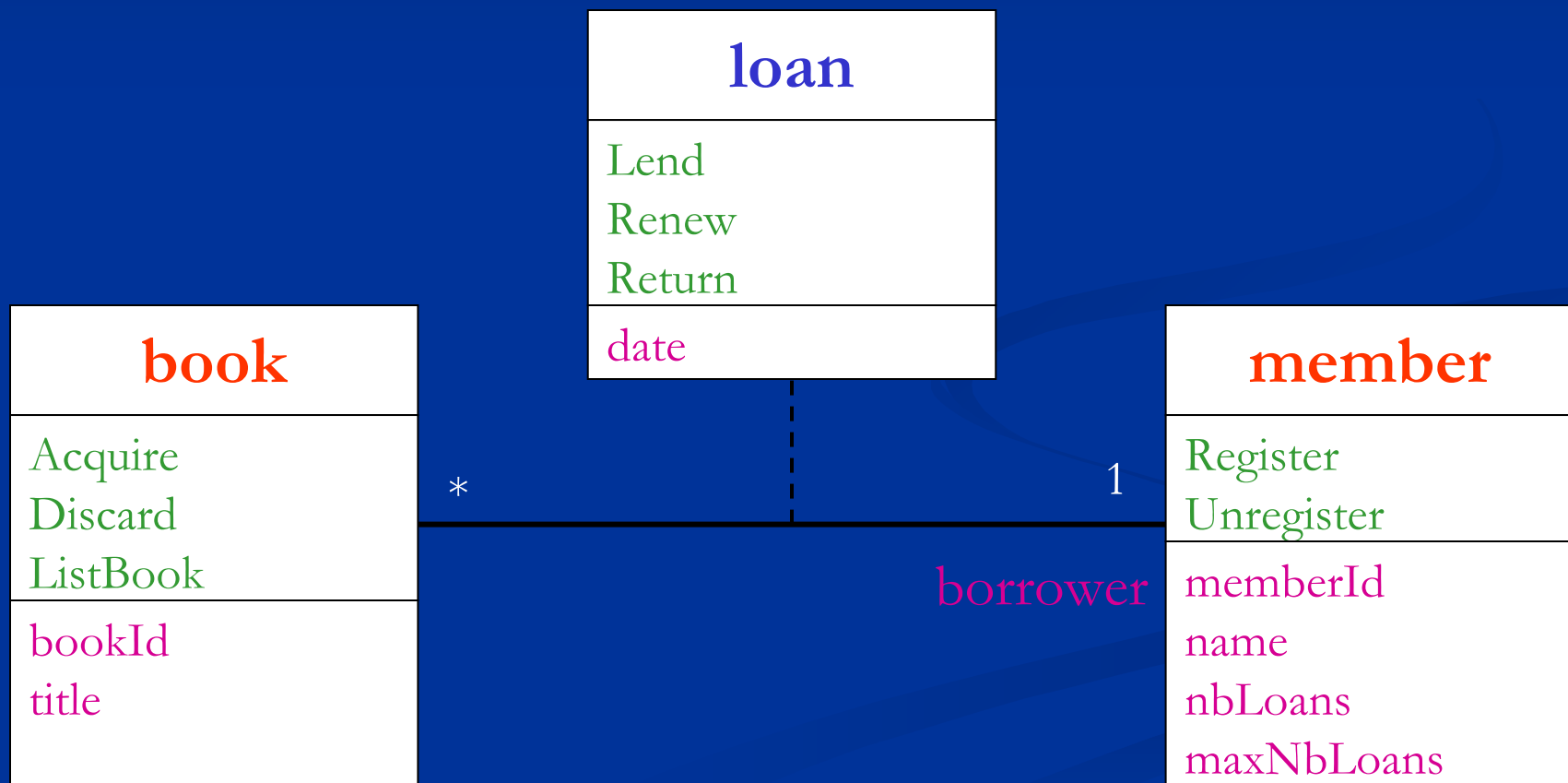
$$|_4 \frac{s \xrightarrow{\sigma, \Gamma}_r s'}{(|_o, \mathbf{snd}, s) \xrightarrow{\sigma, \Gamma} (|_o, \mathbf{snd}, s')}$$

execute the second component
when it has been selected

Choice example



Integration with the business class diagram



State variables

- the system trace is the only state variable
- entity attributes are functions on this trace
- attributes can be used anywhere in ASTDs
 - guard, quantification sets, ...

```
nbLoans(mId : MemberId) =  
  Register(mId, _)      : 0,  
  Lend(mId, _)         : 1 + nbLoans(mId),  
  Return(bId)          : if borrower(bId) = mId  
                        then nbLoans(mId) - 1,  
  Unregister(mId, _)   :  $\perp$ ;
```

Conclusion

- process algebra operators can improve the expressiveness of statecharts
- complete, precise models of information systems
 - not just single instance scenarios, but also multiple instance scenarios
- future work
 - tools for animation
 - model checking
 - code generation